

Test Version A

Instructions: Fill in **A** in the Test Version section. Then enter your NAME, ID Number, CRN (under Class ID) and write **A** (under Test ID) on the op-scan sheet. Darken the appropriate circles below your ID number and Class ID (CRN). **Use a number 2 pencil.** Machine grading may ignore faintly marked circles.

Mark your answers to the test questions in rows 1–14 of the op-scan sheet. Your score on this test will be the number of correct answers. You have one hour to complete this portion of the exam. Turn in the op-scan sheet with your answers, this exam, and all scrap paper at the end of this part of the final exam.

Exam Policies: You may not use a book, notes, formula sheet, or a calculator or computer. Giving or receiving unauthorized aid is an Honor Code Violation.

Signature: _____

Name (printed): _____

Student ID #: _____

1. The rank of the matrix $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 3 & 3 & 3 \end{bmatrix}$ is

- (A) 0. (B) 1. (C) 2. (D) 3.
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2. If $A\mathbf{x} = \begin{bmatrix} 11 \\ 6 \end{bmatrix}$, and $A^{-1} = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix}$, then $\mathbf{x} =$

- (A) $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$. (B) $\begin{bmatrix} -3 \\ -1 \end{bmatrix}$. (C) $\begin{bmatrix} 52 \\ 29 \end{bmatrix}$. (D) $\begin{bmatrix} 77 \\ 24 \end{bmatrix}$.
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3. Which of the following is a steady state vector for the Markov chain with transition matrix P ?

$$P = \begin{bmatrix} 1/5 & 4/5 & 2/5 \\ 1/5 & 0 & 1/5 \\ 3/5 & 1/5 & 2/5 \end{bmatrix}$$

- (A) $\begin{bmatrix} 7 \\ 3 \\ 8 \end{bmatrix}$ (B) $\begin{bmatrix} 4 \\ 0 \\ -4 \end{bmatrix}$ (C) $\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ (D) $\begin{bmatrix} 1 \\ -5 \\ 3 \end{bmatrix}$
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4. Let V be a set of nonzero vectors in \mathbb{R}^n and $S = \text{span}(V)$. Which of the following is **not** possible?

- (A) V is a linearly independent set.
(B) S is a linearly independent set.
(C) Every vector in \mathbb{R}^n is a linear combination of the vectors in V .
(D) Every vector in \mathbb{R}^n is a linear combination of the vectors in S .
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5. Suppose $p(\lambda) = \lambda(\lambda-1)(\lambda+2)(\lambda+1)$ is the characteristic polynomial of a matrix A . Consider the statements:

I: A must be a 4×4 matrix.

II: A can be diagonalized.

III: A is invertible.

Which of the statements I, II, and III are false?

(A) Only I is false.

(C) Only III is false.

(B) Only II is false.

(D) All of I, II, and III are true.

6. Determine whether or not V spans \mathbb{R}^2 and choose a correct justification:

$$V = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}, \text{ where } \mathbf{v}_1 = \begin{bmatrix} 3 \\ -1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 2 \\ 7 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 6 \\ 21 \end{bmatrix}$$

(A) V spans \mathbb{R}^2 because its echelon form contains a leading entry in every column.

(B) V spans \mathbb{R}^2 because $x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + x_3\mathbf{v}_3 = \mathbf{b}$ is consistent for all $\mathbf{b} \in \mathbb{R}^2$.

(C) V does not span \mathbb{R}^2 , because \mathbf{v}_3 is a scalar multiple of \mathbf{v}_2 .

(D) V does not span \mathbb{R}^2 , because a set of three vectors can only span \mathbb{R}^3 .

7. The vectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$, and $\mathbf{v}_3 = \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$ form an orthogonal basis for \mathbb{R}^3 . If

$\mathbf{w} = \begin{bmatrix} 4 \\ -2 \\ 4 \end{bmatrix}$, then the coordinate vector, $[\mathbf{w}]_{\mathcal{B}}$, of \mathbf{w} with respect to the basis $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$

is

(A) $\begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$.

(C) $\begin{bmatrix} 6/\sqrt{3} \\ -6/\sqrt{2} \\ 6/\sqrt{6} \end{bmatrix}$.

(B) $\begin{bmatrix} 6 \\ -6 \\ 6 \end{bmatrix}$.

(D) none of the above.

8. Let $n \geq 2$. How many of the following statements are equivalent to the $n \times n$ matrix A being invertible?

- $\text{rank}(A) \neq 0$.
- The equation $A\mathbf{x} = \mathbf{0}$ has only one solution
- $A = A^T$.
- The reduced row echelon form of A is I_n .
- The rows of A form a basis for \mathbb{R}^n .

(A) One (B) Two (C) Three (D) Four

9. The matrix $A = \begin{bmatrix} 4 & -7 & 2 \\ 3 & 1 & 0 \\ -1 & c & -2 \end{bmatrix}$ is **not** invertible. Determine the value of c .

(A) -6 (B) 6 (C) 8 (D) 10

10. If the system $x_1 - x_3 = 5$, $x_2 + x_3 = 3$, $4x_1 + 3x_2 = 7$ is written in matrix form $A\mathbf{x} = \mathbf{b}$, then the coefficient matrix A is

- (A) $\begin{bmatrix} 1 & -1 & 5 \\ 1 & 1 & 3 \\ 4 & 3 & 7 \end{bmatrix}$.
- (B) $\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 4 & 3 & 0 \end{bmatrix}$.
- (C) $\begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 4 & 3 \end{bmatrix}$.
- (D) $\begin{bmatrix} 1 & 0 & -1 & 5 \\ 0 & 1 & 1 & 3 \\ 4 & 3 & 0 & 7 \end{bmatrix}$.
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11. Let $\mathbf{u} = \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$. The projection of \mathbf{v} onto \mathbf{u} is

- (A) $\begin{bmatrix} 1/5 \\ 0 \\ -3/5 \end{bmatrix}$. (B) $\begin{bmatrix} 2/5 \\ 0 \\ -6/5 \end{bmatrix}$. (C) $\begin{bmatrix} 2/5 \\ 1/5 \\ 0 \end{bmatrix}$. (D) $\begin{bmatrix} 4/5 \\ 2/5 \\ 0 \end{bmatrix}$.
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12. Let $n \geq 2$. Which of the following is true for all $n \times n$ matrices A , B , and C , and $n \times n$ zero matrix O ?

- (A) $AB = BA$. (C) If $AB = O$, then $A = O$ or $B = O$.
(B) If $AB = AC$ then $B = C$. (D) None of the above.
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13. Suppose A is an $m \times n$ matrix, \mathbf{x} and \mathbf{y} are in \mathbb{R}^n , and $A\mathbf{x} = A\mathbf{y}$. Then which of the following statements must be true?

- (A) A is invertible. (C) \mathbf{x} and \mathbf{y} are in $\text{null}(A)$.
(B) $\mathbf{x} = \mathbf{y}$. (D) $\mathbf{y} - \mathbf{x}$ is in $\text{null}(A)$.
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14. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Let \mathbf{u} and \mathbf{v} be two distinct, nonzero vectors in \mathbb{R}^n . Which of the following is sufficient to conclude that T is **not** one-to-one?

- (A) $T(3\mathbf{v}) = T(\mathbf{u})$ (C) $T(\mathbf{v}) = 2T(\mathbf{v}) + T(\mathbf{u})$
(B) $T(3\mathbf{v}) = 2T(\mathbf{u})$ (D) $T(3\mathbf{v}) = 2T(\mathbf{v}) + T(\mathbf{u})$
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